MATH 435 COMPUTER AIDED GEOMETRIC DESIGN Answers for Quiz 5 30.12.2003 Name Student No.

YOU must write GOOD Mathematics, clearly explaining each step of your proof. Otherwise, no objection will be accepted.

1. Given three points $\mathbf{p}_0, \mathbf{p}_1$ and \mathbf{p}_2 in \mathbb{R}^2 . Find the Bézier points $\mathbf{b}_0, \mathbf{b}_1$ and \mathbf{b}_2 , and $\mathbf{x}(t)$ so that the Bézier curve $\mathbf{x}(t)$ passes through (*interpolate*) the data points. (*Hint: Set the parameter values* $t_i = i/n$)

SOLUTION We want to find a curve x(t) satisfying

$$\mathbf{x}(t) = \sum_{i=0}^{n=2} \mathbf{b}_i B_i^n(t), \qquad \mathbf{x}(t_0) = \mathbf{p}_0, \mathbf{x}(t_1) = \mathbf{p}_1, x(t_2) = \mathbf{p}_2.$$

In order to determine the Bézier points, we select $t_0 = 0, t_1 = 1/2$ and $t_2 = 1$ (uniform knot sequence makes calculations easy). Following the end point interpolation property of the basis functions, t = 0 gives $b_0 = p_0$ and t = 1 gives $b_2 = p_2$. At the parameter value t = 1/2, we have

$$\frac{1}{4}\mathsf{b}_0 + \frac{1}{2}\mathsf{b}_1 + \frac{1}{4}\mathsf{b}_2 = \mathsf{p}_1$$

which yields

$$\mathsf{b}_1 = \frac{1}{2}(-4\mathsf{p}_0 + 4\mathsf{p}_1 - \mathsf{p}_2).$$

Finally, the interpolating polynomial for these parameter values is

$$\mathbf{x}(t) = \mathbf{p}_0 B_0^2(t) + \frac{1}{2}(-4\mathbf{p}_0 + 4\mathbf{p}_1 - \mathbf{p}_2)B_1^2(t) + \mathbf{p}_0 B_2^2(t).$$

Note that a linear system of equation could also be used to solve the problem. Namely, solve

1	0	0	$[b_0]$		p_0	
$\frac{1}{4}$	$\frac{1}{2}$	$\frac{1}{4}$	$ b_1 $	=	p_1	
0	0	1	$\lfloor b_2 \rfloor$		p_2	

2. Given two points $\mathbf{p}_0, \mathbf{p}_1$ and a tangent vector \mathbf{m}_0 at \mathbf{p}_0 in \mathbb{R}^2 . Find the Bézier points $\mathbf{b}_0, \mathbf{b}_1$ and \mathbf{b}_2 , and $\mathbf{x}(t)$ so that the Bézier curve $\mathbf{x}(t)$ passes through (*interpolate*) the data points.

SOLUTION We want to find a curve, (namely the Hermite interpolating curve) x(t) satisfying

$$\mathbf{x}(t) = \sum_{i=0}^{n=2} \mathbf{b}_i B_i^n(t), \quad \mathbf{x}(0) = \mathbf{p}_0, \mathbf{x}(1) = \mathbf{p}_1 \text{ and } \dot{\mathbf{x}}(0) = \mathbf{m}_0.$$

Recall that the derivative of a Bézier curve is

$$\dot{\mathbf{x}}(0) = n \sum_{i=0}^{n-1} \Delta \mathbf{b}_i B_i^{n-1}(t).$$

The two points are obtained right away, $x(0) = b_0 = p_0$ and $x(1) = b_2 = p_1$. Using the derivative formula we obtain the third point

$$\dot{\mathsf{x}}(0) = 2\Delta \mathsf{b}_0 = 2(\mathsf{b}_1 - \mathsf{b}_0) = \mathbf{m}_0, \quad \mathsf{b}_1 = \mathsf{p}_0 + \frac{1}{2}\mathbf{m}_0.$$

Thus the Hermite interpolating curve is

$$\mathbf{x}(t) = \mathbf{p}_0 B_0^2(t) + (\mathbf{p}_0 + \frac{1}{2}\mathbf{m}_0)B_1^2(t) + \mathbf{p}_1 B_2^2(t).$$